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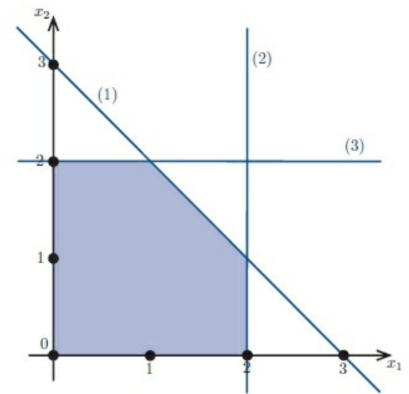
LARSON—OPER 731—CLASSROOM WORKSHEET 08
The Geometry of Linear Programs

Concepts

- (Sec. 2.4) *basis, basic variable, nonbasic variable, basic solution, basic feasible solution, canonical form.*
 - (Sec. 2.8) *hyperplane, halfspace, line, line segment, convex, polyhedron, tight inequality, extreme point*
1. If we have a feasible LP, in SEF, how can we find an initial basis, and initial basic feasible solution?

Geometry

$$\begin{array}{ll} \max & (c_1, c_2)x \\ \text{s.t.} & \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 1 \\ -1 & 0 \\ 0 & -1 \end{pmatrix} x \leq \begin{pmatrix} 3 \\ 2 \\ 2 \\ 0 \\ 0 \end{pmatrix}. \end{array} \quad \begin{array}{l} (1) \\ (2) \\ (3) \\ (4) \\ (5) \end{array}$$



2. What is a *hyperplane* in \mathbb{R}^n ?
3. What is a *halfspace* in \mathbb{R}^n ?
4. Why are hyperplanes in \mathbb{R}^n $(n - 1)$ -dimensional?
5. What is a *polyhedron* in \mathbb{R}^n ?

6. What is the *line* through points $x^{(1)}$ and $x^{(2)}$ in \mathbb{R}^n ?

7. What is the *line segment* through points $x^{(1)}$ and $x^{(2)}$ in \mathbb{R}^n ?

8. When is a set $C \subseteq \mathbb{R}^n$ *convex*?

9. **Claim:** Halfspaces are convex.

10. **Claim:** The intersection of halfspaces is convex.

11. **Claim:** Polyhedra are convex.

12. What is an *extreme point* of a polyhedron?

13. When is an inequality $\alpha^T x = \beta$ *tight* for a point \bar{x} .

14. **Notation:** What is $A^=x \leq b^=$ for a point \bar{x} ?